

# Package ‘AMAPVox’

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**Type** Package

**Title** LiDAR Data Voxelisation

**Version** 0.10.0

**Description** Read, manipulate and write voxel spaces. Voxel spaces are read from text-based output files of the 'AMAPVox' software. 'AMAPVox' is a LiDAR point cloud voxelisation software that aims at estimating leaf area through several theoretical/numerical approaches. See more in the article Vincent et al. (2017) <[doi:10.23708/1AJNMP](https://doi.org/10.23708/1AJNMP)> and the technical note Vincent et al. (2021) <[doi:10.23708/1AJNMP](https://doi.org/10.23708/1AJNMP)>.

**License** CeCILL (>= 2)

**URL** <https://amapvox.org>

**BugReports** <https://github.com/umr-amap/AMAPVox/issues>

**Depends** R (>= 4.0.0)

**Imports** curl, data.table, dplyr, methods, rappdirs, rvest, stringr, utils

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**Author** Grégoire Vincent [aut],  
Julien Heurtebize [aut],  
Philippe Verley [aut, cre]

**Maintainer** Philippe Verley <philippe.verley@ird.fr>

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AMAPVox

*AMAPVox package*

---

## Description

The package provides a a set of R functions for working with voxel spaces (read, write, plot, etc.). Voxel spaces are read from text-based output files of the [AMAPVox software](#).

## References

- Research paper first describing AMAPVox:  
Vincent, G., Antin, C., Laurans, M., Heurtebize, J., Durrieu, S., Lavalley, C., & Dauzat, J. (2017). Mapping plant area index of tropical evergreen forest by airborne laser scanning. A cross-validation study using LAI2200 optical sensor. *Remote Sensing of Environment*, 198, 254-266. doi: [10.1016/j.rse.2017.05.034](https://doi.org/10.1016/j.rse.2017.05.034)
- Up-to-date description of PAD/LAD estimators implemented in AMAPVox:  
VINCENT, Gregoire; PIMONT, François; VERLEY, Philippe, 2021, "A note on PAD/LAD estimators implemented in AMAPVox 1.7", doi: [10.23708/1AJNMP](https://doi.org/10.23708/1AJNMP), DataSuds, V1

## Contact

<contact@amapvox.org>

## Author(s)

Philippe VERLEY <philippe.verley@ird.fr>

## See Also

Useful links:

- <https://amapvox.org>
- Report bugs at <https://github.com/umr-amap/AMAPVox/issues>

---

butterfly

*Identify butterflies from a `VoxelSpace` object.*

---

## Description

Identify butterflies from a `VoxelSpace-class` object.

A butterfly refers to a non-empty isolated voxel. Non-empty means that there is one or more hits recorded in the voxel. Isolated means that voxels in the **Moore neighborhood** of rank 1 are empty (no hit).

## Usage

```
butterfly(vxsp)
```

## Arguments

`vxsp` a `VoxelSpace-class` object

## Value

a list of voxel index (i, j, k) identified as butterfly in a `data.table::data.table`

**See Also**[clear](#)**Examples**

```
# load a voxel file
vxsp <- readVoxelSpace(system.file("extdata", "tls_sample.vox", package = "AMAPVox"))
# identify butterflies
btf <- butterfly(vxsp)
# clear butterflies
clear(vxsp, butterfly(vxsp))
```

---

canopy

*Extract canopy from voxel space.*

---

**Description**

Extract canopy from [VoxelSpace-class](#) object. The canopy layer is the set of highest voxels with number of hits greater than a user-defined threshold.

**Minimum number of hits/echos:**

Minimum number of hits is set by default to one, meaning that a single echo in a voxel is enough to consider that there is some vegetation. Increasing this threshold will tend to lower the canopy level or introduce some gaps ( i-j-cells with no vegetation). This `hit.min` filter is stronger than [butterfly](#) since it does not discriminate isolated voxels. A reasonable value for `hit.min` cannot be suggested ad-hoc since it strongly depends on sampling intensity. Removing butterflies prior to extracting canopy is advisable.

**Gaps:**

For a `VoxelSpace` with fully defined ground level (see [ground](#)), missing canopy cells can be interpreted as gaps. Conversely if both ground and canopy are missing for a i-j-cell, then it is inconclusive.

**Above/below canopy:**

Function `aboveCanopy` returns voxel index above canopy level (excluded). Function `belowCanopy` returns voxel index below canopy level (included).

**Canopy Height Model:**

Function `canopyHeight` returns ground distance at canopy level, including gaps.

**Usage**

```
canopy(vxsp, hit.min = 1)
```

```
belowCanopy(vxsp, ...)
```

```
aboveCanopy(vxsp, ...)
```

```
canopyHeight(vxsp, ...)
```

**Arguments**

<code>vxsp</code>	a <a href="#">VoxelSpace-class</a> object.
<code>hit.min</code>	a positive integer, minimum number of hit/echo in a voxel to consider it contains vegetation.
<code>...</code>	additional parameters which will be passed to canopy function. So far only <code>hit.min</code> parameter.

**Value**

[data.table::data.table](#) object with voxel index either below canopy, canopy level or above canopy

**See Also**

[butterfly](#), [ground](#)

**Examples**

```
vxsp <- readVoxelSpace(system.file("extdata", "tls_sample.vox", package = "AMAPVox"))
cnp <- canopy(vxsp)
acnp <- aboveCanopy(vxsp)
bcnp <- belowCanopy(vxsp)
# canopy layer included in below canopy subset
all(bcnp[cnp, on=list(i, j, k)] == cnp) # TRUE expected
vxsp@data[cnp, list(i, j, ground_distance), on=list(i, j, k)]
```

---

clear

*Clear voxel*

---

**Description**

Clear a set of voxels. Clearing means that the state variables of the selected voxels are altered as if they were *clear* of any vegetation. Namely:

- number of echo set to zero
- intercepted beam surface set to zero (if variable is outputted)
- plant area density set to zero (if variable is outputted)
- transmittance set to one (if variable is outputted)
- any attenuation variable set to zero

Other state variables such as sampling intensity, mean angle, entering beam surface, etc. are unaltered. A cleared voxel is not the same as an unsampled voxel (not "crossed" by any beam).

**Usage**

```

clear(vxsp, vx)

## S4 method for signature 'VoxelSpace,data.table'
clear(vxsp, vx)

## S4 method for signature 'VoxelSpace,vector'
clear(vxsp, vx)

## S4 method for signature 'VoxelSpace,matrix'
clear(vxsp, vx)

```

**Arguments**

vxsp            a [VoxelSpace-class](#) object.

vx              (i, j, k) voxel coordinates as a [data.table::data.table](#) with i, j, k columns, a vector (i, j, k) or a matrix with i, j, k columns.

**Examples**

```

# load a voxel file
vxsp <- readVoxelSpace(system.file("extdata", "tls_sample.vox", package = "AMAPVox"))
# clear 1st voxel
clear(vxsp, c(0, 0, 0)) # clear 1st voxel
# clear butterflies
clear(vxsp, butterfly(vxsp))
# clear voxels with less than two hits
clear(vxsp, vxsp@data[nbEchos < 2])

```

---

computeG

*Foliage projection ratio  $G(\theta)$ .*


---

**Description**

Compute the mean projection of unit leaf area on the plane perpendicular to beam direction, namely,  $G(\theta)$  parameter. Assumption of symmetric distribution of leaf azimuth angle. When estimating  $G$  for large amount of the  $\theta$  values, it is advised to enable the lookup table for speeding up the calculation.

**Usage**

```

computeG(
  theta,
  pdf = "spherical",
  chi,
  mu,

```

```

    nu,
    with.lut = length(theta) > 100,
    lut.precision = 0.001
  )

```

### Arguments

theta	a numeric vector, theta, the incident beam inclination, in radian, ranging [0, pi/2].
pdf	the name of the probability density function of the leaf angle distribution. One of "uniform", "spherical", "planophile", "erectophile", "plagiophile", "extremophile", "ellipsoidal", "twoParamBeta". Refer to section "Leaf Angle Distribution functions" for details.
chi	a float, parameter of the ellipsoidal leaf angle distribution. The ratio the ratio horizontal axis over vertical axis. See section "Leaf Angle Distribution functions" for details.
mu	a float, parameter controlling the Beta distribution. See section "Leaf Angle Distribution functions" for details.
nu	a float, parameter controlling the Beta distribution. See section "Leaf Angle Distribution functions" for details.
with.lut	a Boolean, whether to estimate G with a lookup table (LUT). By default the lookup table is automatically generated when length of theta vector is greater than 100.
lut.precision	a float, the increment of the theta sequence ranging from 0 to pi/2 for computing the lookup table.

### Details

#### Leaf Angle Distribution functions

- de Wit's leaf angle distribution functions:
  - **uniform**, proportion of leaf angle is the same at any angle
  - **spherical**, relative frequency of leaf angle is the same as for surface elements of a sphere
  - **planophile**, horizontal leaves most frequent
  - **erectophile**, vertical leaves most frequent
  - **plagiophile**, oblique leaves most frequent
  - **extremophile**, oblique leaves least frequent
- **ellipsoidal** distribution function, generalization of the spherical distribution over an ellipsoid. Relative frequency of leaf angle is the same as for surface elements of an ellipsoid. Takes one parameter chi the ratio horizontal axis over vertical axis. For chi = 1 the distribution becomes spherical. For chi < 1, the ellipsoid is a prolate spheroid (like a rugby ball). For chi > 1 the ellipsoid is an oblate spheroid (a sphere that bulges at the equator and is somewhat squashed at the poles).
- **two parameters Beta** distribution. Most generic approach from Goal and Strebel (1984) to represent large variety of leaf angle distribution. Takes two parameters mu and nu that control the shape of the Beta distribution.

## References

Wang, W. M., Li, Z. L., & Su, H. B. (2007). Comparison of leaf angle distribution functions: effects on extinction coefficient and fraction of sunlit foliage. *Agricultural and Forest Meteorology*, 143(1), 106-122.

## See Also

[plotG\(\)](#)

## Examples

```
# G(theta) == 0.5 for spherical distribution
all(computeG(theta = runif(10, 0, pi/2)) == 0.5) # returns TRUE
# ellipsoidal distribution
computeG(theta = runif(10, 0, pi/2), pdf = "ellipsoidal", chi = 0.6)
```

---

crop

*Crop voxel space*

---

## Description

Crop [VoxelSpace-class](#) object based on voxel i, j, k, index. If cropping index are missing, the function will automatically crop the voxel space by discarding outermost unsampled slices of voxels. A *slice* designates a layer with constant i (i-slice), j (j-slice) or k (k-slice). *unsampled* means that no pulse went through.

One may want to crop the voxel space on coordinates rather than grid index. To do so the voxel space must be first converted to an *sf* object and use the [sf::st\\_crop](#) function.

```
vxsp <- readVoxelSpace(system.file("extdata", "tls_sample.vox", package = "AMAPVox"))
vxsp@data[, c("x", "y"):=getPosition(vxsp)[, .(x, y)]]
library(sf)
vx.sf <- sf::st_as_sf(vxsp@data, coords=c("x", "y"))
vx.sf <- sf::st_crop(vx.sf, c(xmin = 4, ymin = 1, xmax = 5, ymax = 4))
sf::st_bbox(vx.sf)
vxsp@data <- sf::st_drop_geometry(vx.sf)
```

## Usage

```
crop(vxsp, imin = 0, imax = Inf, jmin = 0, jmax = Inf, kmin = 0, kmax = Inf)
```

## Arguments

<code>vxsp</code>	a <a href="#">VoxelSpace-class</a> object.
<code>imin</code>	minimum i index of cropped area (inclusive)
<code>imax</code>	maximum i index of cropped area (inclusive)
<code>jmin</code>	minimum j index of cropped area (inclusive)



jmax	maximum j index of cropped area (inclusive)
kmin	minimum k index of cropped area (inclusive)
kmax	maximum k index of cropped area (inclusive)

**Value**

Cropped voxel space with updated i, j, k grid coordinates and updated header (min and max corner).

**Examples**

```
## Not run:
vxsp <- readVoxelSpace(system.file("extdata", "tls_sample.vox", package = "AMAPVox"))
plot(crop(vxsp, imin = 1, imax = 5))
# introduce unsampled areas in voxel space
vxsp@data[i < 3, nbSampling:= 0]
# automatic cropping
plot(crop(vxsp))

## End(Not run)
```

---

 Extract

---

*Extract or Replace Parts of a VoxelSpace Object*


---

**Description**

Operators acting on VoxelSpace object. If user attempts

**Usage**

```
## S4 method for signature 'VoxelSpace'
x$name

## S4 method for signature 'VoxelSpace,ANY,missing'
x[[i, j, ...]]

## S4 replacement method for signature 'VoxelSpace'
x$name <- value

## S4 replacement method for signature 'VoxelSpace,ANY,missing,ANY'
x[[i, j]] <- value

## S4 replacement method for signature 'VoxelSpace'
x$name <- value
```

**Arguments**

x	A VoxelSpace object
name	A literal character string or a name (possibly backtick quoted).
i	string, name of elements to extract.
j	Unused.
...	Unused.
value	typically an array-like R object of a similar class as x.

**Examples**

```
# load a voxel file
vxsp <- readVoxelSpace(system.file("extdata", "tls_sample.vox", package = "AMAPVox"))

# extract columns or header parameters
vxsp$nbSampling
vxsp[["i"]]
vxsp[["mincorner"]]

## Not run:
# add new column
vxsp[["pad_capped"]] <- ifelse(vxsp$PadBVTotal > 0.5, 0.5, vxsp$PadBVTotal)
# update header parameter
vxsp[["max_pad"]] <- 0.5

## End(Not run)
```

---

fillNA

---

*Fill missing values (NA) with averaged neighboring data*


---

**Description**

Fill missing values of a given variable in a VoxelSpace object with averaged neighboring values.

Neighboring values are selected among voxels within a user-defined radius in meter and whose sampling rate (number of pulses that went through the voxel) is above a user-defined threshold. Distance between voxels is the euclidian distance between voxel centers. Fill-value may be capped by user-defined minimal and maximal values.

Default radius (if not defined by user) is set to largest dimension of voxel size `max(getVoxelSize(vxsp))`. It guarantees that default neighborhood is isotropic.

In some cases, for instance poorly sampled area, neighboring values may all be missing or discarded. A fallback value can be provided to "force fill" such voxels. An other option is to run again the function with larger radius or lower sampling threshold.

**Usage**

```
fillNA(
  vxsp,
  variable.name,
  variable.min = -Inf,
  variable.max = Inf,
  variable.fallback,
  radius,
  pulse.min = 10
)
```

**Arguments**

<code>vxsp</code>	a <a href="#">VoxelSpace-class</a> object.
<code>variable.name</code>	a character, the name of a variable in the <code>VoxelSpace</code>
<code>variable.min</code>	a numeric, minimal value for the fill values
<code>variable.max</code>	a numeric, maximal value for the fill values
<code>variable.fallback</code>	a numeric, optional fallback value in case no fill value can be estimated from neighboring voxels.
<code>radius</code>	a numeric, the radius in meter that defines the neighborhood of a voxel. The function looks for the voxels whose center is inside a sphere of radius <code>radius</code> centered at current voxel center. Default is set to <code>max(getVoxelSize(vxsp))</code>
<code>pulse.min</code>	a numeric, minimal sampling intensity (i.e. number of pulses that went through a voxel) to include neighboring voxel in the estimation of the averaged fill value.

**Examples**

```
# read voxel space
vxsp <- readVoxelSpace(system.file("extdata", "tls_sample.vox", package = "AMAPVox"))
# Randomly add some NA in PAD variable
vx <- vxsp@data
ind <- sample(vx[PadBVTotals > 0, which = TRUE], 3)
# print initial values
vx[ind, .(i, j, k, PadBVTotals)]
vx[ind, PadBVTotals := NA]
# fill NA in PAD variable
fillNA(vxsp, "PadBVTotals", variable.max = 5)
# print filled values
vx[ind, .(i, j, k, PadBVTotals)]
```

---

getLocalVersions	<i>List local AMAPVox versions.</i>
------------------	-------------------------------------

---

### Description

List AMAPVox versions already installed on your computer by the package. AMAPVox versions are installed in the user-specific data directory, as specified by [user\\_data\\_dir](#).

### Usage

```
getLocalVersions()
```

### Value

a data.frame with 2 variables: \$version that stores the version number and \$path the local path of the AMAPVox directory.

### See Also

[getRemoteVersions](#), [user\\_data\\_dir](#)

---

getMaxCorner	<i>Gets the x, y, z coordinates of the voxel space top right corner.</i>
--------------	--

---

### Description

Gets the x, y, z coordinates of the voxel space top right corner.

### Usage

```
getMaxCorner(vxsp)
```

```
## S4 method for signature 'VoxelSpace'
getMaxCorner(vxsp)
```

### Arguments

vxsp            the [VoxelSpace-class](#) object.

### Value

the x, y, z coordinates of the voxel space top right corner, as a numerical vector.

**Examples**

```
# load a voxel file
vxsp <- readVoxelSpace(system.file("extdata", "tls_sample.vox", package = "AMAPVox"))
# retrieve 'max_corner' parameter
getMaxCorner(vxsp)
```

---

getMinCorner	<i>Gets the x, y, z coordinates of the voxel space bottom left corner.</i>
--------------	--

---

**Description**

Gets the x, y, z coordinates of the voxel space bottom left corner.

**Usage**

```
getMinCorner(vxsp)

## S4 method for signature 'VoxelSpace'
getMinCorner(vxsp)
```

**Arguments**

vxsp            the [VoxelSpace-class](#) object.

**Value**

the x, y, z coordinates of the voxel space bottom left corner, as a numerical vector.

**Examples**

```
# load a voxel file
vxsp <- readVoxelSpace(system.file("extdata", "tls_sample.vox", package = "AMAPVox"))
# retrieve 'min_corner' parameter
getMinCorner(vxsp)
```

---

getParameter	<i>Gets a parameter from the VoxelSpace header.</i>
--------------	---

---

**Description**

Gets a parameter from the VoxelSpace header.

**Usage**

```
getParameter(vxsp, what)

## S4 method for signature 'VoxelSpace,character'
getParameter(vxsp, what)

## S4 method for signature 'VoxelSpace,missing'
getParameter(vxsp, what)
```

**Arguments**

vxsp            the [VoxelSpace-class](#) object  
 what            the name of the parameter. If missing returns all parameters.

**Value**

the parameter as a character

**See Also**

[VoxelSpace-class](#);

**Examples**

```
# load a voxel file
vxsp <- readVoxelSpace(system.file("extdata", "tls_sample.vox", package = "AMAPVox"))
# show parameters name
names(getParameter(vxsp))
# retrieve 'mincorner' parameter
getParameter(vxsp, "mincorner")
# all parameters
getParameter(vxsp)
```

---

getPosition

*Gets the x, y, z coordinates of a given voxel.*

---

**Description**

Gets the x, y, z coordinates of the voxel center. If the voxel parameter is missing, it returns the positions of all the voxels in the voxel space.

**Usage**

```
getPosition(vxsp, vx)

## S4 method for signature 'VoxelSpace,vector'
getPosition(vxsp, vx)
```

```
## S4 method for signature 'VoxelSpace,matrix'
getPosition(vxsp, vx)

## S4 method for signature 'VoxelSpace,data.table'
getPosition(vxsp, vx)

## S4 method for signature 'VoxelSpace,missing'
getPosition(vxsp, vx)
```

### Arguments

`vxsp` a [VoxelSpace-class](#) object.

`vx` (i, j, k) voxel coordinates as a [data.table::data.table](#) with i, j, k columns, a vector (i, j, k) or a matrix with i, j, k columns.

### Value

the x, y, z coordinates of the voxel center.

### Examples

```
# load a voxel file
vxsp <- readVoxelSpace(system.file("extdata", "tls_sample.vox", package = "AMAPVox"))

# get position of voxel(i=0, j=0, k=0)
getPosition(vxsp, c(0, 0, 0))

# get position of voxels 1 to 10 in the data.table
getPosition(vxsp, vxsp@data[1:10,])

# get positions of every voxel
getPosition(vxsp)
```

---

getRemoteVersions      *List remote AMAPVox versions.*

---

### Description

List AMAPVox versions available for download from page <https://amap-dev.cirad.fr/projects/amapvox/files>

### Usage

```
getRemoteVersions()
```

### Value

a `data.frame` with 2 variables: `$version` that stores the version number and `$url` the URL of the associated ZIP file.

**See Also**

[getLocalVersions](#)

---

getVoxelSize	<i>Gets the elemental size of a voxel (dx, dy, dz) in meter.</i>
--------------	--

---

**Description**

Gets the elemental size of a voxel (dx, dy, dz) in meter.

**Usage**

```
getVoxelSize(vxsp)

## S4 method for signature 'VoxelSpace'
getVoxelSize(vxsp)
```

**Arguments**

vxsp            the [VoxelSpace-class](#) object.

**Value**

the size of the voxel in meter, as a numerical vector.

**Examples**

```
# load a voxel file
vxsp <- readVoxelSpace(system.file("extdata", "tls_sample.vox", package = "AMAPVox"))
# retrieve voxel size
getVoxelSize(vxsp)
```

---

ground	<i>Extract ground from voxel space.</i>
--------	---

---

**Description**

Extract ground layer from [VoxelSpace-class](#) object.

**Ground layer:**

The ground layer is the set of voxels that are just above ground level. The bottom facet of the voxel must be above ground `ground_distance(voxel_center) >= dz/2` with `dz` the voxel size on `z` axis. Ground layer may be missing (the function returns an empty `data.table`) or incomplete (the function returns a `data.table` with `nrow(ground(vxsp)) < prod(dim(vxsp)[1:2])`) for some voxel space.



**Above/below ground:**

Function `aboveGround` returns voxel index above ground layer (included). Function `belowGround` returns voxel index below ground layer (excluded).

**Ground energy:**

Function `groundEnergy` estimates fraction of light reaching the ground. It is computed as the ratio of entering beam section on potential beam section (beams that would have crossed a voxel if there were no vegetation in the scene). It requires variables `bsEntering` and `bsPotential`.

**Ground elevation:**

Function `groundElevation` returns the elevation of the ground layer. It is provided as a check function, to make sure that AMAPVox *digital elevation model* is consistent with the one provided in input.

**Usage**

```
ground(vxsp)
belowGround(vxsp)
aboveGround(vxsp)
groundEnergy(vxsp)
groundElevation(vxsp)
```

**Arguments**

`vxsp` a [VoxelSpace-class](#) object.

**Value**

[data.table::data.table](#) object with voxel index either below ground, ground level or above ground.

**Examples**

```
vxsp <- readVoxelSpace(system.file("extdata", "tls_sample.vox", package = "AMAPVox"))
gr <- ground(vxsp)
ag <- aboveGround(vxsp)
bg <- belowGround(vxsp) # empty in test case
# ground layer included in above ground subset
all(ag[gr, on=list(i, j, k)] == gr) # TRUE expected
vxsp@data[ag, on=list(i, j, k)]
```

gui

*Run AMAPVox Graphical User Interface.***Description**

Run AMAPVox Graphical User Interface (GUI). The function embeds a version manager for installing locally any version available remotely. AMAPVox GUI relies on Java 1.8 64-Bit and JavaFX. See detailed section below.

**Usage**

```
gui(
  version = "latest",
  check.update = TRUE,
  java = "java",
  jvm.options = "-Xms2048m",
  stdout = ""
)
```

**Arguments**

version,	either "latest" or a valid version number major.minor(.build) if version="latest" and check.update=FALSE or no internet connection it runs latest local version.
check.update,	check for newer version online and install it.
java	Path to the java executable. Default 'java' value assumes that java is correctly defined on the \$PATH variable.
jvm.options	JVM (Java Virtual Machine) options. By default it allocates 2Go of heap memory to AMAPVox.
stdout	where output to both stdout/stderr should be sent. Same as stdout & stderr options from function <a href="#">system2</a> .

**Java 1.8 64-Bit with JavaFX**

AMAPVox GUI relies on Java 1.8 64-Bit and JavaFX. In practice it requires either [Java 1.8 64-Bit Oracle](#) or [Java 1.8 64-Bit Corretto](#). OpenJDK 8 will not work since JavaFX is not included. You may check beforehand if java is installed on your system and which version.

```
system2("java", args = "-version")
```

If AMAPVox::gui keeps throwing errors after you have installed suitable Java 1.8 64-Bit, it means that Java 1.8 may not be properly detected by your system. In such case you may have to check and set the JAVA\_HOME environment variable.

```
Sys.getenv("JAVA_HOME")
Sys.setenv(JAVA_HOME="path/to/java/1.8/bin")
system2("java", args = "-version")
```

As a last resort you may change the `java` parameter of this function and set the full path to Java 1.8 binary.

```
AMAPVox::gui(java = "/path/to/java/1.8/bin/java")
```

### See Also

[getLocalVersions](#), [getRemoteVersions](#), [installVersion](#), [removeVersion](#)

### Examples

```
## Not run:
# install and run latest AMAPVox version
AMAPVox::gui()
# install and run version 1.6.4 for instance
AMAPVox::gui(version="1.6.4", check.update = FALSE)

## End(Not run)
```

---

installVersion	<i>Install specific AMAPVox version on local computer.</i>
----------------	--

---

### Description

Install specific AMAPVox version on your computer. AMAPVox versions are installed in the user-specific data directory, as specified by `user_data_dir`. You should not worry to call directly the `install` function since local installations are automatically handled by the version manager when you launch AMAPVox GUI with `gui` function.

### Usage

```
installVersion(version, overwrite = FALSE)
```

### Arguments

`version`, a valid and existing AMAPVox remote version number (major.minor.build)  
`overwrite`, whether existing local installation should be re-installed.

### Value

the path of the AMAPVox installation directory.

### See Also

[getLocalVersions](#), [getRemoteVersions](#), [removeVersion](#)  
[user\\_data\\_dir](#)

**Examples**

```
## Not run:
# install latest version
installVersion(tail(getRemoteVersions())$version, 1))

## End(Not run)
```

---

<code>merge.VoxelSpace</code>	<i>Merge two voxel spaces</i>
-------------------------------	-------------------------------

---

**Description**

Merge of two [VoxelSpace-class](#) object. Voxel spaces must have same spital extension and resolution, and some shared column names.

**Merging modes:**

Variables `i`, `j`, `k` & `ground_distance` are merged.

Variables `nbEchos`, `nbSampling`, `lgTotal`, `bsEntering`, `bsIntercepted`, `bsPotential`, `weightedEffectiveFreepathL` & `weightedFreepathLength` are summed-up.

Variables `sdLength`, `angleMean` and `distLaser` are weighted means with `nbSampling` (the number of pulses) as weights.

Attenuation FPL variables (`attenuation_FPL_biasedMLE`, `attenuation_FPL_biasCorrection`, `attenuation_FPL_unb` & `lMeanTotal` are calculated analytically.

Transmittance and attenuation variables (except the FPL attenuation variables listed above) are weighted means with `bsEntering` as weights.

Any other variables will not be merged. In particular PAD variables are not merged and should be recalculated with [plantAreaDensity](#) on the merged voxel space. E.g: `vxsp <- plantAreaDensity(merge(vxsp1, vxsp2))`

**Merging multiple voxel spaces:**

Merging several voxel spaces works as follow : `vxsp1` and `vxsp2` merged into `vxsp12`. `vxsp12` & `vxsp3` merged into `vxsp123`, etc. The process can be synthetized with the [base::Reduce](#) function.

```
vxsp <- Reduce(merge, list(vxsp1, vxsp2, vxsp3))
```

**Usage**

```
## S3 method for class 'VoxelSpace'
merge(x, y, ...)
```

**Arguments**

<code>x</code> , <code>y</code>	<a href="#">VoxelSpace-class</a> objects to be merged.
<code>...</code>	Not used

**Value**

A merged [VoxelSpace-class](#) object.

**Examples**

```
# merge same voxel space to confirm merging behavior
vxsp1 <- readVoxelSpace(system.file("extdata", "tls_sample.vox", package = "AMAPVox"))
vxsp2 <- readVoxelSpace(system.file("extdata", "tls_sample.vox", package = "AMAPVox"))
vxsp <- merge(vxsp1, vxsp2)
all(vxsp$nbSampling == vxsp1$nbSampling + vxsp2$nbSampling)

# with PAD
vxsp <- plantAreaDensity(merge(vxsp1, vxsp2), pulse.min = 1)
all((vxsp$pad_transmittance - vxsp1$padBVTotal) < 1e-7) # equal at float precision
```

---

plantAreaDensity	<i>Plant Area Density (PAD)</i>
------------------	---------------------------------

---

**Description**

Computes Plant Area Density either from transmittance or attenuation coefficient estimates. Details of calculation and underlying assumptions can be found online at doi: [10.23708/1AJNMP](https://doi.org/10.23708/1AJNMP). PAD is defined as the plant area per unit volume ( PAD plant area / voxel volume =  $m^2 / m^3$ ).

**Usage**

```
plantAreaDensity(
  vxsp,
  lad = "spherical",
  angle.name = "angleMean",
  variable.name = c("transmittance", "attenuation_FPL_unbiasedMLE",
    "attenuation_PPL_MLE"),
  pad.max = 5,
  pulse.min = 5,
  ...
)
```

**Arguments**

vxsp	a <a href="#">VoxelSpace-class</a> object.
lad	the name of the probability density function of the leaf angle distribution. One of <code>AMAPVox:::leafAngleDistribution</code> .
angle.name	the name of the mean angle variable in the VoxelSpace object.
variable.name	the name of the transmittance/attenuation variables in the VoxelSpace object. Transmittance variables are expected to start with "tra" and attenuation variables with "att".
pad.max	a float, the maximal PAD value
pulse.min	an integer, the minimal number of pulses in a voxel for computing the PAD. PAD set to NA otherwise.
...	additional parameters which will be passed to the leaf angle distribution functions. Details in <a href="#">computeG</a> .

**Value**

A voxel space object with the requested PAD variables.

**References**

VINCENT, Gregoire; PIMONT, François; VERLEY, Philippe, 2021, "A note on PAD/LAD estimators implemented in AMAPVox 1.7", doi: [10.23708/1AJNMP](https://doi.org/10.23708/1AJNMP), DataSuds, V1

**See Also**

[computeG](#)

---

plantAreaIndex	<i>Plant Area Index (PAI)</i>
----------------	-------------------------------

---

**Description**

Computes Plant Area Index (PAI) from Plant Area Density (PAD). PAI is defined as the plant area per unit ground surface area ( $PAI = \text{plant area} / \text{ground area} = m^2 / m^2$ ).

The function can estimate PAI on the whole voxel space or any region of interest (parameter `vx` subset of voxels). It can compute PAI from several perspectives : either an averaged PAI value, a two-dimensions (i, j) PAI array or vertical profiles either above ground or below canopy.

**Usage**

```
plantAreaIndex(
  vxsp,
  vx,
  type = c("av", "ag", "bc", "xy"),
  pattern.pad = "^pad_*"
)
```

**Arguments**

<code>vxsp</code>	a <a href="#">VoxelSpace-class</a> object.
<code>vx</code>	a subset of voxel index. A data.table with i, j, k columns. Missing parameter means whole voxel space.
<code>type</code>	a character vector, the type of PAI profile. <ul style="list-style-type: none"> <li>• "av" Averaged value on every voxel</li> <li>• "ag" Above ground vertical profile</li> <li>• "bc" Below canopy vertical profile</li> <li>• "xy" Spatial profile</li> </ul>
<code>pattern.pad</code>	character string containing a <a href="#">regular expression</a> to be matched in the voxel space variable names, for selecting PAD variables. Typing the name of a specific PAD variable works just fine.

**Value**

Returns a list of PAI profiles for requested PAD variables and PAI types.

**av Averaged PAI:**

Returns a single value. Calculated as the sum of PAD values multiplied by voxel volume and divided by ground surface with vegetation.

**ag & bc Above ground and below canopy PAI vertical profile:**

Returns a vertical profile of PAI values either from ground distance or canopy depth. Calculated as the averaged PAD values per layer (a layer being defined by either the distance to ground or canopy level) multiplied by voxel size along z (equivalent to multiplying PAD by voxel volume and dividing by voxel ground surface).

**xy Spatial PAI profile:**

Returns a list a PAI values by i, j index. Calculated as the sum of PAD on (i, j) column multiplied by voxel size along z (equivalent to multiplying PAD by voxel volume and dividing by voxel ground surface).

**See Also**

[plantAreaDensity](#)

**Examples**

```
vxsp <- readVoxelSpace(system.file("extdata", "tls_sample.vox", package = "AMAPVox"))
vxsp <- plantAreaDensity(vxsp)
## Not run:
lai <- plantAreaIndex(vxsp)
names(lai)
library(ggplot2)
ggplot(data = lai[["pad_transmittance.pai.ag" ]], aes(x=pai, y=ground_distance)) +
  geom_path() + geom_point()

## End(Not run)
# PAI on a subset
ni <- round(dim(vxsp)[1]/2)
vx <- vxsp@data[i < ni, .(i, j, k)]
lai <- plantAreaIndex(vxsp, vx)
```

---

plot

*Plot an object of class VoxelSpace*

---

**Description**

plot a [VoxelSpace-class](#) object.

**Usage**

```
plot(x, y, ...)

## S4 method for signature 'VoxelSpace,missing'
plot(
  x,
  y,
  variable.name = "nbSampling",
  palette = "viridis",
  bg.color = "lightgrey",
  width = 640,
  voxel.size = 5,
  unsampled.discard = TRUE,
  empty.discard = TRUE,
  ...
)
```

**Arguments**

<code>x</code>	the object of class <code>VoxelSpace</code> to plot
<code>y</code>	Unused (inherited from R base)
<code>...</code>	additional parameters which will be passed to <a href="#">plot3d</a> .
<code>variable.name</code>	character, the name of the variable to plot
<code>palette</code>	character, a valid palette name (one of <code>hcl.pals()</code> )
<code>bg.color</code>	character, a valid background color name (one of <code>colors()</code> )
<code>width</code>	numeric, the width of the windows
<code>voxel.size</code>	numeric, the size of voxel in pixels
<code>unsampled.discard</code>	logical, whether to discard unsampled voxel
<code>empty.discard</code>	logical, whether to discard empty voxel (no hit)

**Details**

Plot an object of class `VoxelSpace` in a 3d device. By default it plots the sampling intensity but the user can choose any variable available in the voxel file.

**See Also**

[plot3d](#)

**Examples**

```
## Not run:
# load a voxel file
vxsp <- readVoxelSpace(system.file("extdata", "tls_sample.vox", package = "AMAPVox"))
# plot sampling intensity by default
```



```

plot(vxsp)
# plot PAD
plot(vxsp, variable.name = "PadBVTotal", palette = "YlOrRd")

## End(Not run)

```

---

plotG	<i>Plot G(theta) profiles for one or several leaf angle distribution functions</i>
-------	--

---

### Description

Plot G(theta) profiles for one or several leaf angle distribution functions with theta in  $[0, \pi/2]$ . Requires ggplot2 package.

### Usage

```
plotG(pdf = leafAngleDistribution, chi = 0.6, mu = 1.1, nu = 1.3)
```

### Arguments

pdf	the name of the leaf angle distribution functions. One of "uniform", "spherical", "planophile", "erectophile", "plagiophile", "extremophile", "ellipsoidal", "twoParamBeta".
chi	a float, parameter of the ellipsoidal leaf angle distribution. The ratio the ratio horizontal axis over vertical axis. See section "Leaf Angle Distribution functions" for details.
mu	a float, parameter controlling the Beta distribution. See section "Leaf Angle Distribution functions" for details.
nu	a float, parameter controlling the Beta distribution. See section "Leaf Angle Distribution functions" for details.

### Examples

```

## Not run:
# plot G(theta) for planophile leaf angle distribution function
AMAPVox::plotG(pdf = "planophile")
# plot G(theta) for every distributions
AMAPVox::plotG()

## End(Not run)

```

---

readVoxelSpace	<i>Read a voxel file</i>
----------------	--------------------------

---

**Description**

read a voxel file and cast it into a [VoxelSpace-class](#) object.

**Usage**

```
readVoxelSpace(f)
```

**Arguments**

f                   The path of the voxel file.

**See Also**

[writeVoxelSpace](#)

**Examples**

```
# load a voxel file
vxsp <- readVoxelSpace(system.file("extdata", "tls_sample.vox", package = "AMAPVox"))
```

---

removeVersion	<i>Remove specific AMAPVox version from local computer.</i>
---------------	---

---

**Description**

Uninstall specific AMAPVox version from your computer.

**Usage**

```
removeVersion(version)
```

**Arguments**

version,            a valid and existing AMAPVox local version number (major.minor.build)

**See Also**

[getLocalVersions](#), [installVersion](#)

## Examples

```
## Not run:  
# uninstall oldest version from your computer  
removeVersion(head(getLocalVersions())$version, 1))  
  
## End(Not run)
```

---

tools

*Tools inherited from base R for VoxelSpace object.*

---

## Description

Tools inherited from base R for [VoxelSpace-class](#) objects.

## Usage

```
## S4 method for signature 'VoxelSpace'  
show(object)  
  
## S3 method for class 'VoxelSpace'  
print(x, ...)  
  
## S3 method for class 'VoxelSpace'  
length(x)  
  
## S3 method for class 'VoxelSpace'  
dim(x)  
  
is.VoxelSpace(x)  
  
## S4 method for signature 'VoxelSpace'  
ncol(x)  
  
## S4 method for signature 'VoxelSpace'  
nrow(x)  
  
## S3 method for class 'VoxelSpace'  
names(x)
```

## Arguments

object	a <a href="#">VoxelSpace-class</a> object.
x	a <a href="#">VoxelSpace-class</a> object.
...	further arguments passed to print function.

**Note on** length.VoxelSpace

AMAPVox allows to discard empty voxels in the voxel file. In such case length.VoxelSpace will return the expected number of voxels as if none were missing. As a consequence the number of voxels stored in the [VoxelSpace-class](#) object may be inferior to the returned value, namely `nrow(x) <= length(x)`

---

toRaster

*Voxel layer to raster*


---

**Description**

Converts a voxel space (i, j) layer into a [terra::SpatRaster](#) object.

**Usage**

```
toRaster(vxsp, vx)
```

**Arguments**

`vxsp` a [VoxelSpace-class](#) object.  
`vx` a voxel space horizontal slice. A `data.table` with `i, j` columns and least one additional variable, the value of the raster layer. Every column beside `i` and `j` will be converted into a raster layer.

**Value**

A [terra::SpatRaster](#) object.

**Examples**

```
## Not run:
vxsp <- readVoxelSpace(system.file("extdata", "tls_sample.vox", package = "AMAPVox"))
library(terra)

# CHM, DEM and PAI as raster
plot(toRaster(vxsp, merge(canopyHeight(vxsp), groundElevation(vxsp), all = T)))

# PAI
vxsp <- plantAreaDensity(vxsp)
pai <- plantAreaIndex(vxsp, type = "xy", pattern.pad = "pad_transmittance")
plot(toRaster(vxsp, pai))

# sampling intensity at 2 meters
plot(toRaster(vxsp, vxsp@data[ground_distance == 2.25, .(i, j, nbSampling)]))

## End(Not run)
```

---

VoxelSpace-class	<i>VoxelSpace</i>
------------------	-------------------

---

**Description**

Class that holds the state variables of every voxel of the voxel space in a [data.table](#), plus metadata from the voxel space header.

**Value**

An object of class VoxelSpace.

**Slots**

file the path of the voxel file (.vox).

data the voxels hold in a data.table.

header a list of parameters associated to this voxel file.

**See Also**

[readVoxelSpace](#)

---

writeVoxelSpace	<i>Write a voxel file</i>
-----------------	---------------------------

---

**Description**

write a voxel file out of a [VoxelSpace-class](#) object.

**Usage**

```
writeVoxelSpace(vxsp, f)
```

**Arguments**

vxsp the object of class VoxelSpace to write

f a character string naming a file.

**See Also**

[readVoxelSpace](#)

**Examples**

```
## Not run:  
# load a voxel file  
vxsp <- readVoxelSpace(system.file("extdata", "tls_sample.vox", package = "AMAPVox"))  
# set max PAD to 5  
vxsp@data[, PadBVTotal:=sapply(PadBVTotal, min, 5)]  
# write updated voxel file in temporary file  
writeVoxelSpace(vxsp, tempfile("pattern="amapvox_", fileext=".vox"))  
  
## End(Not run)
```

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